

**Exercise 6.1**

Compute Laplace transform of the convolution integral

$$f(x) = \int_0^x dy e^{x-y} \sin(y).$$

**Solution:**

Noticing that

$$f(x) = \int_0^x e^{x-y} \sin(y) dy = e^x * \sin(x),$$

then by Equation (154), we get that

$$\mathcal{L}\{f(x)\}(s) = \mathcal{L}\{e^x * \sin(x)\}(s) = \mathcal{L}\{e^x\}(s) \mathcal{L}\{\sin(x)\}(s).$$

From Examples 5.1 and 5.2,

$$\mathcal{L}\{e^x\}(s) \mathcal{L}\{\sin(x)\}(s) = \frac{1}{s-1} \cdot \frac{1}{s^2+1} = \frac{1}{(s^2+1)(s-1)}.$$

*3 points: the result seems to be correct.*

## Exercise 6.2

Find the inverse Laplace transform for

$$g(s) = \frac{1}{(s+2)(s^2+5s+6)}$$

Apply again the previously computed transforms and the result (155) for product of two Laplace transforms.

### Solution:

From the Laplace transforms table,

$$\mathcal{L}\{e^{-3x}\}(s) = \frac{1}{s+3} \quad \text{and} \quad \mathcal{L}\{xe^{-2x}\}(s) = \frac{1}{(s+2)^2}.$$

By (155) and integration by parts,

$$\begin{aligned} \mathcal{L}^{-1}\{g(s)\}(x) &= \mathcal{L}^{-1}\left\{\frac{1}{(s+2)^2} \cdot \frac{1}{s+3}\right\}(x) = \mathcal{L}^{-1}\{\mathcal{L}\{xe^{-2x}\}(s) \mathcal{L}\{e^{-3x}\}(s)\}(x) \\ &= \int_0^x ye^{-2y}e^{-3(x-y)} dy = e^{-3x} \int ye^y dy = e^{-3x} \left( [ye^y]_0^x - \int_0^x e^y dy \right) \\ &= e^{-3x} (1 + xe^x - e^x). \end{aligned}$$

*3 points: the result looks correct.*

### Exercise 6.3

Find the solution for differential equation

$$y''(x) + 5y'(x) + 6y(x) = e^{-2x}$$

with initial conditions  $y(0) = 0$ ,  $y'(0) = 0$  using Laplace transform.

**Solution:**

Since the Laplace transform is linear, taking the Laplace transform of the left-hand side of the DE and using the derivative rule yields

$$\begin{aligned}\mathcal{L}\{y'' + 5y' + 6y\}(s) &= s\mathcal{L}\{y'\}(s) - y'(0) + 5s\mathcal{L}\{y\}(s) - 5y(0) + 6\mathcal{L}\{y\}(s) \\ &= s^2\mathcal{L}\{y\}(s) - sy(0) + 5s\mathcal{L}\{y\}(s) + 6\mathcal{L}\{y\}(s) \\ &= s^2\mathcal{L}\{y\}(s) + 5s\mathcal{L}\{y\}(s) + 6\mathcal{L}\{y\}(s).\end{aligned}$$

Similarly, the Laplace transform of the right-hand side of the DE gives

$$\mathcal{L}\{e^{-2x}\}(s) = \frac{1}{s+2}.$$

Equating the two and solving for  $\mathcal{L}\{y\}(s)$  gives us

$$\mathcal{L}\{y\}(s) = \frac{1}{(s+2)(s^2+5s+6)}.$$

By the previous exercise,

$$\mathcal{L}^{-1}\left\{\frac{1}{(s+2)(s^2+5s+6)}\right\}(x) = e^{-3x}(1 + xe^x - e^x).$$

Therefore

$$y(x) = \mathcal{L}^{-1}\left\{\frac{1}{(s+2)(s^2+5s+6)}\right\}(x) = e^{-3x}(1 + xe^x - e^x),$$

which by differentiation is indeed the solution.

*3 points: the result should be correct.*

## Exercise 6.4

Use Laplace transform to find the solution for differential equation

$$y''(x) + 4y(x) = \sin(2x)$$

corresponding to initial conditions  $y(0) = 0$  and  $y'(0) = -2$ .

### Solution:

The Laplace transform of the RHS is by linearity and the derivative rule

$$\begin{aligned}\mathcal{L}\{y'' + 4y\}(s) &= s\mathcal{L}\{y'\}(s) - y'(0) + 4\mathcal{L}\{y\}(s) \\ &= s^2\mathcal{L}\{y\}(s) - sy(0) + 2 + 4\mathcal{L}\{y\}(s) \\ &= s^2\mathcal{L}\{y\}(s) + 4\mathcal{L}\{y\}(s) + 2\end{aligned}$$

and similarly, the Laplace transform of the LHS using known transforms becomes

$$\mathcal{L}\{\sin(2x)\}(s) = \frac{2}{s^2 + 4}.$$

We can now set the two equal, which gives

$$s^2\mathcal{L}\{y\}(s) + 4\mathcal{L}\{y\}(s) + 2 = \frac{2}{s^2 + 4}.$$

Solving for  $\mathcal{L}\{y\}(s)$  gives

$$\mathcal{L}\{y\}(s) = \frac{2}{(s^2 + 4)^2} - \frac{2}{s^2 + 4}.$$

Now, by linearity and the convolution theorem,

$$\begin{aligned}
\mathcal{L}^{-1} \left\{ \frac{s}{(s^2+4)^2} - \frac{2}{s^2+4} \right\} (x) &= \mathcal{L}^{-1} \left\{ \frac{1}{2} \left( \frac{2}{s^2+4} \cdot \frac{2}{s^2+4} \right) \right\} (x) - \sin(2x) \\
&= \frac{1}{2} \mathcal{L}^{-1} \{ \mathcal{L} \{ \sin(2x) \} (s) \mathcal{L} \{ \sin(x) \} (s) \} (x) - \sin(2x) \\
&= \frac{1}{2} \int_0^x \sin(2y) \sin(2(x-y)) \, dy - \sin(2x) \\
&= \frac{1}{4} \int_0^x 2 \sin \left( \frac{1}{2}(4y - 2x + 2x) \right) \sin \left( \frac{1}{2}(2x + 2x - 4y) \right) \, dy - \sin(2x) \\
&= \frac{1}{4} \int_0^x (\cos(4y - 2x) - \cos(2x)) \, dy - \sin(2x) \\
&= \frac{1}{16} \int_{-2x}^{2x} \cos(u) \, du - \frac{1}{4} x \cos(2x) - \sin(2x) \\
&= \frac{1}{16} (\sin(2x) - \sin(-2x)) - \frac{1}{4} x \cos(2x) - \sin(2x) \\
&= \frac{1}{8} \sin(2x) - \frac{1}{4} x \cos(2x) - \sin(2x) \\
&= -\frac{7}{8} \sin(2x) - \frac{1}{4} x \cos(2x).
\end{aligned}$$

Therefore

$$y(x) = -\frac{7}{8} \sin(2x) - \frac{1}{4} x \cos(2x).$$

Plugging  $y(x)$  back to the DE shows that it is indeed the solution.

*3 points: the result should be correct.*

## Exercise 6.5

Use Laplace transform to solve differential equations

$$y''(x) + \omega^2 y(x) = a(1 - \theta(x - b))$$

with initial conditions  $y(0) = 0$  and  $y'(0) = 0$  and  $a, b > 0$ . Verify this explicitly by inserting the obtained solution to the equation (which is useful to do every time).

**Solution:**

By linearity and the derivative rule, taking the Laplace transform of the LHS gives

$$\begin{aligned}\mathcal{L}\{y'' + \omega^2 y\}(s) &= s\mathcal{L}\{y'\}(s) - y'(0) + \omega^2 \mathcal{L}\{y\}(s) \\ &= s^2 \mathcal{L}\{y\}(s) - sy(0) + \omega^2 \mathcal{L}\{y\}(s) \\ &= s^2 \mathcal{L}\{y\}(s) + \omega^2 \mathcal{L}\{y\}(s) \\ &= \mathcal{L}\{y\}(s)(s^2 + \omega^2)\end{aligned}$$

and similarly, using known transforms, the Laplace transform of the RHS is

$$\begin{aligned}\mathcal{L}\{a(1 - \theta(x - b))\}(s) &= a(\mathcal{L}\{1\}(s) - \mathcal{L}\{\theta(x - b)\}(s)) \\ &= a\left(\frac{1}{s} - \frac{e^{-sb}}{s}\right) \\ &= \frac{a}{s}(1 - e^{-sb}).\end{aligned}$$

Setting the two transforms equal to each other and solving for  $\mathcal{L}\{y\}(s)$  gives

$$\begin{aligned}\mathcal{L}\{y\}(s) &= \frac{a(1 - e^{-sb})}{s(s^2 + \omega^2)} \\ &= \frac{a}{s} \frac{1}{s^2 + \omega^2} (1 - e^{-sb}) \\ &= \frac{1}{\omega} \frac{a}{s} \frac{\omega}{s^2 + \omega^2} (1 - e^{-sb}) \\ &= \frac{1}{\omega} \frac{a}{s} \frac{\omega}{s^2 + \omega^2} - \frac{a}{\omega} \frac{\omega}{s^2 + \omega^2} \frac{e^{-sb}}{s}.\end{aligned}$$

Therefore, by linearity, known transforms and the convolution theorem,

$$\begin{aligned}
\mathcal{L}^{-1} \left\{ \frac{a(1 - e^{-sb})}{s(s^2 + \omega^2)} \right\} (x) &= \frac{1}{\omega} \mathcal{L}^{-1} \{ \mathcal{L} \{a\} (s) \mathcal{L} \{ \sin(\omega x) \} (s) \} (x) - \frac{a}{\omega} \mathcal{L}^{-1} \{ \mathcal{L} \{ \sin(\omega x) \} (s) \mathcal{L} \{ \theta(x - b) \} (s) \} (x) \\
&= \frac{1}{\omega} \int_0^x a \sin(\omega y) \, dy - \frac{a}{\omega} \int_0^x \theta(x - b) \sin(\omega(x - y)) \, dy \\
&= \frac{a}{\omega^2} (1 - \cos(\omega x)) + \frac{a}{\omega} \theta(x - b) \int_b^x \sin(\omega(y - x)) \, dy \\
&= \frac{a}{\omega^2} (1 - \cos(\omega x)) - \frac{a}{\omega} \theta(x - b) \int_0^{b-x} \sin(\omega u) \, du \\
&= \frac{a}{\omega^2} (1 - \cos(\omega x)) - \frac{a}{\omega^2} (1 - \cos(\omega(b - x))) \theta(x - b).
\end{aligned}$$

Therefore

$$y(x) = \frac{a}{\omega^2} (1 - \cos(\omega x) + (\cos(\omega(b - x)) - 1) \theta(x - b))$$

and thus

$$\begin{aligned}
y'(x) &= \frac{a}{\omega^2} (\omega \sin(\omega x) + \omega \sin(\omega(b - x)) \theta(b - x) + \overbrace{\delta(x - b) (\cos(\omega(b - x)) - 1)}^{=0}) \\
&= \frac{a}{\omega^2} (\omega \sin(\omega x) + \omega \sin(\omega(b - x)) \theta(x - b))
\end{aligned}$$

and

$$\begin{aligned}
y''(x) &= \frac{a}{\omega^2} (\omega^2 \cos(\omega x) - \omega^2 \cos(\omega(b - x)) \theta(x - b) + \overbrace{\omega \sin(\omega(b - x)) \delta(x - b)}^{=0}) \\
&= \frac{a}{\omega^2} (\omega^2 \cos(\omega x) - \omega^2 \cos(\omega(b - x)) \theta(x - b)).
\end{aligned}$$

Now

$$\begin{aligned}
y'' + \omega^2 y &= a \cos(\omega x) - a \cos(\omega(b - x)) \theta(x - b) + a - a \cos(\omega x) + a \cos(\omega(x - b)) \theta(x - b) - a \theta(x - b) \\
&= a(1 - \theta(x - b))
\end{aligned}$$

as expected.

*3 points: the desired result was reached with steps.*